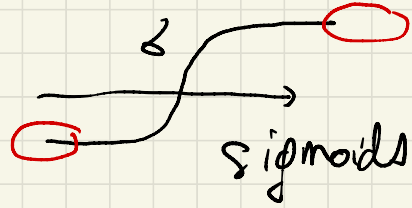


Recap : MLP

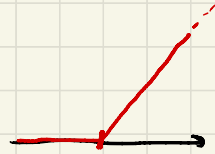


$$x_{k+1} = \sigma(W_R x_k + b_k)$$

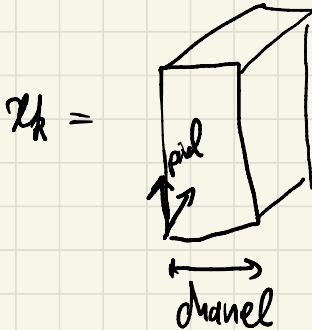
$$\Theta_k = (W_R, b_k)$$



$$\sigma(x) = \begin{cases} \text{Arctan}(x) \\ \frac{e^x}{1+e^x} \end{cases} \quad \sigma(x) = \text{Relu}(x)$$



Design choices : "Weight sharing" \rightarrow convolution
audio/image/video

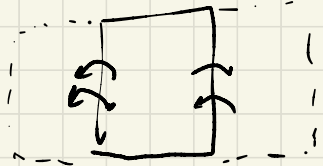


$$W_k = \left(\begin{matrix} \alpha \\ \beta \end{matrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right)_{S=1}^S$$

"Translation" inv. operator \Leftrightarrow convolution"

$$T_\tau : x[\cdot, \cdot, \cdot] \rightsquigarrow n[\cdot, \tau_1, \cdot, \tau_2, \cdot]$$

$\underbrace{\quad}_{\text{pixel}} \rightarrow \text{channel}$



Thm: $W : \mathbb{R}^{M \times M \times S} \rightarrow \mathbb{R}^{M \times M \times T}$

that commutes with trans^o

$$W \circ T_\tau = T_\tau \circ W$$

$$\begin{array}{ccc}
 n & \xrightarrow{W} & Wn \\
 \downarrow T_\tau & & \uparrow T_\tau \\
 & \xrightarrow{W} &
 \end{array}$$

so that

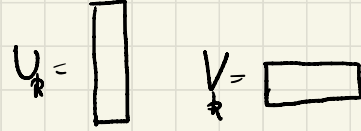
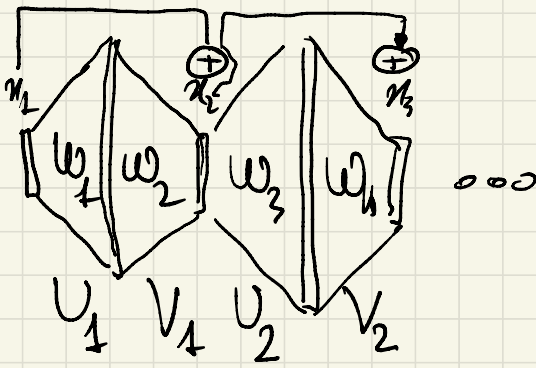
if and only if $\{\psi_{st}\}_{\substack{s=1 \dots S \\ t=1 \dots T}}$

$$Wn = \left(\sum_s \psi_{st} * x[\cdot, \cdot, s] \right)_t$$

example: 1.1 conv^o

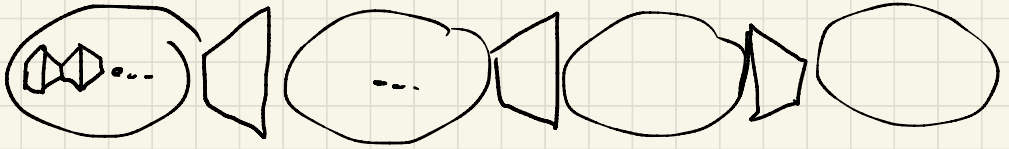
2nd design choice: skip connex^o

Res-Net



$$x_{k+1} = x_k + \sigma \left[V_k \sigma \left[U_k x_k \right] \right]$$

↑
removed / batch norm



[Generative net

[U-Net \rightarrow sept. generative model
diff. $\frac{d}{dt}$]

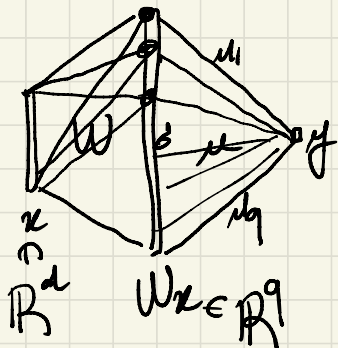
Transformers : convolst + nonlinearity \rightarrow Attention

"Theory": Universality / Expressivity

2 layers NN

"Linear" single layer

$q = \# \text{neurons}$



$$y = \left\langle \mu_k, \underbrace{\sigma(Wx)}_{\in \mathbb{R}^q} \right\rangle$$

\mathbb{R}^q

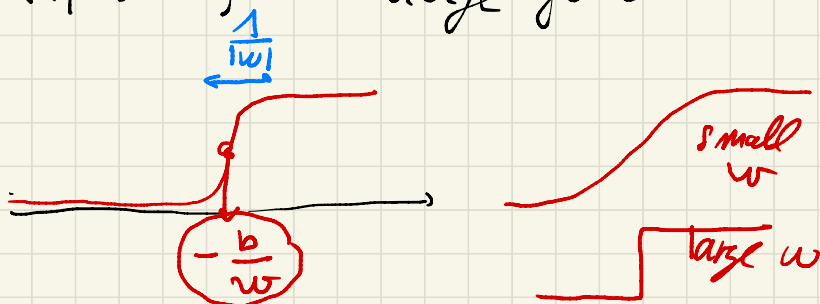
$$y = \sum_k \mu_k \sigma(\langle x, w_k \rangle + b_k)$$

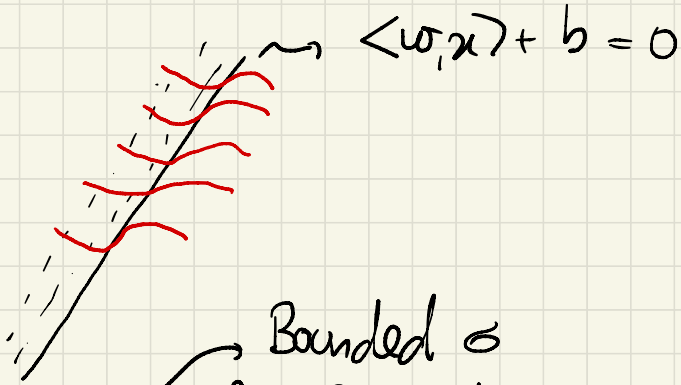
$$W = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \end{bmatrix}$$

$$\varphi(x) = \sum_k \mu_k \varphi_{w_k, b_k}(x)$$

$\varphi_{w, b}(x) = \sigma(\langle x, w \rangle + b)$ "Ridge funct^o"

1-D



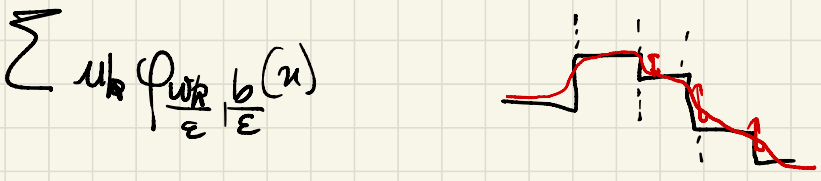
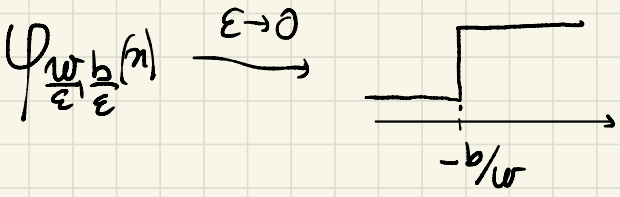


Thm: [Cibenko] if $f(x)$ continuous, $\epsilon > 0$ precision,
 $R > 0$, $\exists q = \# \text{neurons}$, $\exists \begin{matrix} w \\ b \end{matrix}$

Bounded σ

such that, $\forall \|x\| \leq R \quad \left| f(x) - \sum_{k=1}^q u_k \varphi_{\frac{w_k}{R}, \frac{b_k}{R}}(x) \right| \leq \epsilon$

NN. q neurons.



Speed of approx. · No free lunch

Barron's function: $\hat{f}(\omega) = \int f(x) \cdot e^{-i\langle \omega, x \rangle} dx$
↑
Frequency

Barron's norm: $\|f\|_B \triangleq \int \|\omega\| \cdot |\hat{f}(\omega)| d\omega$

Sobolev norm: $\|f\|_{W^{1,2}}^2 = \int \|\omega\|^2 \cdot \|\hat{f}(\omega)\|^2 d\omega$ †

$$\begin{aligned} \hat{f}'(\omega) &= i\omega \cdot \hat{f}(\omega) \\ &= \int \|\hat{f}'(\omega)\|^2 d\omega \\ &= \int |f'(x)|^2 dx = \|f'\|_{L^2}^2 \end{aligned}$$

Thm: If $\|f\|_B < +\infty$ $R > 0$ radius then $\forall \epsilon > 0, \exists$ a neural net $f_q(x) = \sum_{k=1}^q \psi_{k, \omega_k}(x)$ such that



$$\sqrt{\frac{1}{|B(R)|} \int_{B(x)} |f(x) - f_q(x)|^2 dx} \leq \frac{\|f\|_B}{\sqrt{q}} = \epsilon$$

↑
Loss

with pol.

$$\frac{\|f\|_{\text{rob}}}{q^{1/d}} = \epsilon$$

← curse of the dim^s.

⊕ No curse of dim, explicit

⊖ 2 layers.

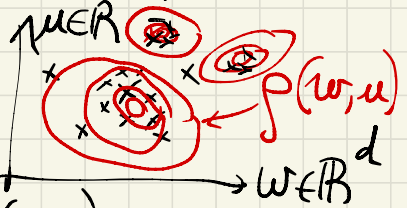
⊖ existence, how to find f_q

Proof: mean field analysis.

$$f_q(x) = \frac{1}{q} \sum_{k=1}^q \mu_k \sigma(\langle x, w_k \rangle)$$

↓ $q \rightarrow +\infty$

$$\Theta_k = (\mu_k, w_k) \in \mathbb{R}^{d+1}$$



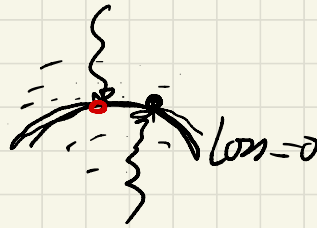
$$f^{\text{sp}}(x) = \int \mu \sigma(\langle x, w \rangle) d\rho(w, u)$$

Difficult: $\|f\|_3 < +\infty \Leftrightarrow \exists f, f = \int f^{\text{sp}}$

Q: optimiz^o. Chizat / Bach.

if $q \rightarrow \infty$, GD on the loss

Q: How many neurons ($q=33$)

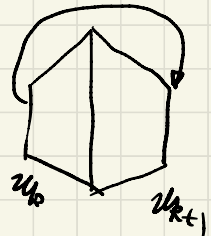


Q: Generaliz^o \rightarrow Implicit bias.

Deep & Wide ResNet.

$$z_{k+1} = z_k + \frac{1}{K} V_k \in \mathbb{R}^q$$

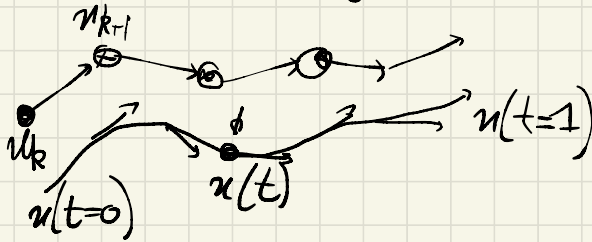
$K=1 \dots \textcircled{K}$
Depth



$\left\{ \begin{array}{l} K = \text{depth} \\ q = \text{width} \end{array} \right.$ " $\rightarrow \infty$ " mean fixed

$$\textcircled{*} \quad \frac{u_{k+1} - u_k}{1/k} = \nabla_{\theta_k}(u_k) \quad \theta_k = (U_k, V_k)$$

$$\nabla_{\theta}(u) = U \sigma(Vx)$$



" $K \rightarrow +\infty$ "

$$u(t) = \nabla_{\theta(t)}(u(t))$$

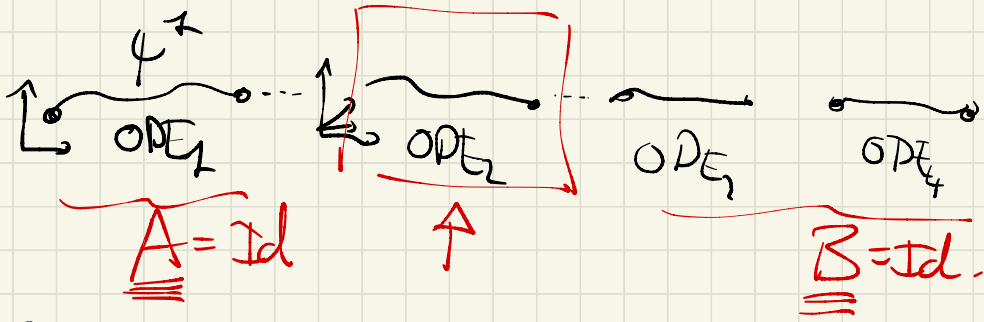
out: $u(1)$

$$u(t=0) = x_0$$

inf. depth limit: $\psi_{\theta} : x(0) \rightarrow x(1)$
 $\theta \uparrow ??$ learning??

$$\left(x_i \right)_{i=1}^N \rightarrow \left(y_i \right)_{i=1}^N$$

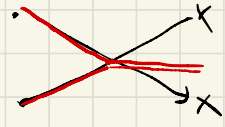
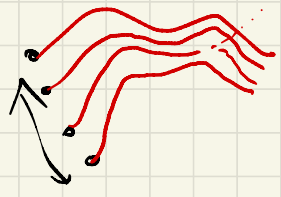
learn: $\min_{\{\theta(t)\}_{t=0}^T} E(\theta) = \frac{1}{N} \sum_{i=1}^N \ell(\psi_{\theta}(x_i), y_i)^2$



Thms: Barani Neups 2022

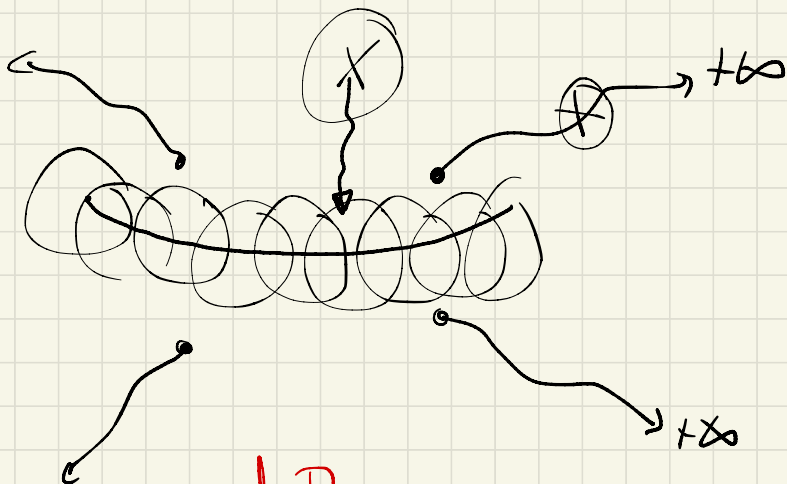
$$C(\theta) \cdot \|\nabla E(\theta)\|^2 \stackrel{(2)}{\leq} E(\theta) - E(\theta^*) \stackrel{(1)}{\leq} C(\|\theta\|) \cdot \|\nabla E(\theta)\|^2$$

\uparrow
 P-L
 Poljak - Tjojajevitch.



① \Rightarrow No loc. min. but $w \rightarrow +\infty$

② \Rightarrow if θ "close" to θ^* $w \not\rightarrow +\infty$

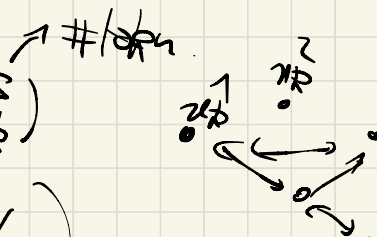


$$A \in \mathbb{R}^{d \times d}$$

D large enough

$$x_{k+1} = \mathcal{U}_{\theta_k}(x_k)$$

$$x_k = (x_k^1, x_k^2, \dots, x_k^s)$$

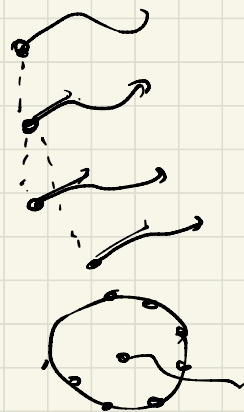


$$x_{k+1} = x_k + \frac{1}{k} A_{\theta_k}(x_k)$$

$$x^i(t) = A_{\theta(t)}(x(t))$$

$$x^i(t) = \mathcal{U}_{\theta(t)}(x^i(t))$$

$$x_i \rightarrow \frac{x_i - m_i}{\| \cdot \|}$$



$$v_{\mathbb{Q}^n}(\tilde{x}_i, (x^2)) = \sum_j A_{ij} \cdot (Vx_j)$$

(K, \mathbb{Q}, V)
 $\sum_j A_{ij}$
Hand

$$A_{ij} = e^{\langle Kx_i, \mathbb{Q}x_j \rangle}$$

