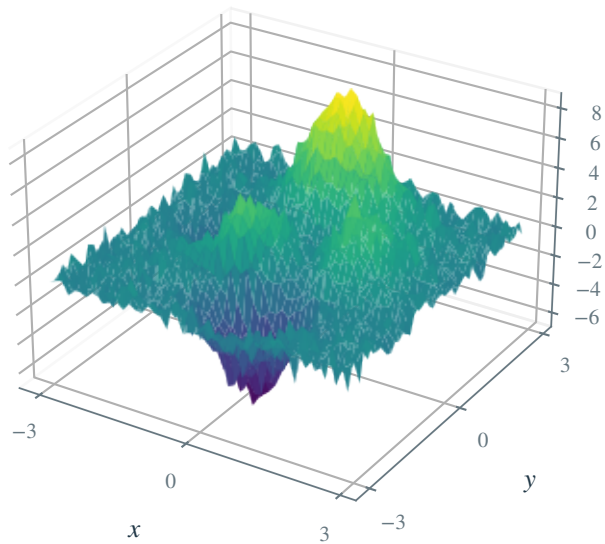
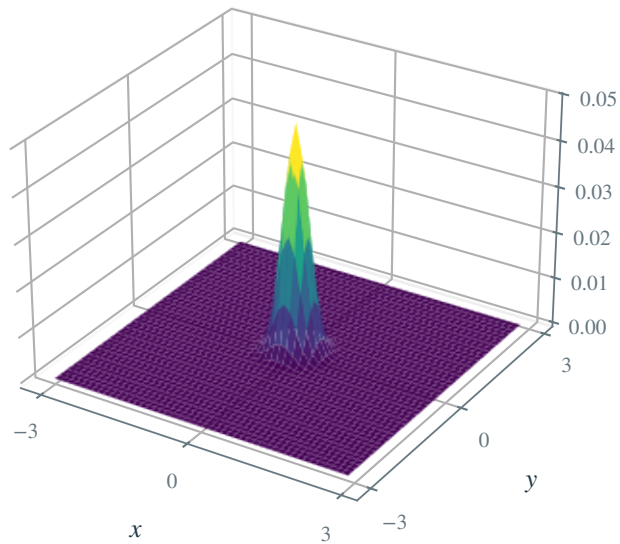


Noisy surface f



Unit-sum Gaussian g



Circular convolution $f * g$

